

**Lab 3: Static Panel Models**  
**Econometrics Beyond Ordinary Least Squares**

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WS 2020/2021

Panel Data combines aspects of time series and cross-sectional econometric analysis.

We will have to deal with multi-dimensional group-specific effects.

Popular examples:

- ▶ Longitudinal Surveys
- ▶ Cross-Country Macro analysis
- ▶ Experiments rolled out in multiple waves (Why do researchers do that?)

## OLS: Unbiasedness and Efficiency

**Unbiasedness:**  $E[\hat{\beta}] = \beta \Leftrightarrow E[\epsilon_i | X_i] = E[\epsilon_i] = 0$ .

**Efficiency:**  $Var(\hat{\beta}) \leq Var(\beta^*) \quad \forall \beta^* \neq \hat{\beta} \Leftrightarrow V[\hat{\epsilon}_i] = \sigma^2 \quad \forall i \in N; Cov[\epsilon_i, \epsilon_j] = 0 \quad \forall i \neq j \in N$ .

Under Gauss-Markov Conditions 1 through 4,  $\hat{\beta}_{OLS} = (X'X)^{-1}X'y$  is the **best unbiased linear estimator (BLUE)**.

If  $E[\epsilon_i | X_i] \neq 0$  or if the **covariance matrix** of  $\epsilon$  has no uniform diagonal and only zero off-diagonal entries, we **cannot guarantee BLUE**.

$$\Sigma_{\epsilon} = \begin{bmatrix} \sigma^2 & 0 & 0 \\ 0 & \sigma^2 & 0 \\ 0 & 0 & \sigma^2 \end{bmatrix} \quad (1)$$

## Panel Data: Big Questions

- ▶ Time Component: Did something happen that year?
- ▶ Serial Correlation: Cyclical Over- and undershooting?
- ▶ Dynamic Effects: last year's investment and this year's output?
- ▶ Group Effects: What if unobserved effects aren't completely independent?
- ▶ Advantages of Panels: Number of observations, dynamic effects, group effects
- ▶ Disadvantages of Panels: Small-sample properties of estimators, robusticity

## Panel Data: Representation

You have observations  $(y_{it}, x_{it})$  for individuals  $i \in I$  and periods  $t \in T$ . Estimate the impact of  $x$  on  $y$ .

Most general formulation of a model (not much generality in meaning):

$$y_{it} = \alpha_{it} + x'_{it}\beta_{it} + \epsilon_{it} \quad (2)$$

- ▶ Strengths: Complex, Precise, allows for heterogeneity
- ▶ Weaknesses: No generalization

Simpler panel model:

$$y_{it} = \alpha + x'_{it}\beta + \epsilon_{it} \quad (3)$$

We cannot assume  $\epsilon_{it}$  to be independent and identically distributed (“**i.i.d.**”), and specifically not  $\epsilon_{it} \sim N(0, \sigma^2)$ , if  $i$  and  $t$  are meaningful.

In face of auto-correlation: Construct **Newey-West pooled errors** for groups  $i \in g \in G$ .

$$y_{it} = \alpha + x'_{it}\beta + \epsilon_{it} \quad (4)$$

$$\epsilon_{it} \sim N(0, \sigma_g) \quad (5)$$

$$\hat{V}(\hat{\beta}_k) = [X'X]^{-1} \left[ \sum_c x'_c \hat{\epsilon}'_c \hat{\epsilon}_c x_c \right] [X'X]^{-1}$$

## Panel Data: Fixed and Random Effects

**Fixed Effects:** Cross-sectional units can have unobserved, **mean-shifting** effects, eg. social connections favoring promotions. This allows for **no common intercept term**.

Think of: Runners starting from somewhere behind the starting line.

$$y_{it} = \alpha_i + \beta' x_{it} + \epsilon_{it} ; \epsilon_{it} \mid IID(0, \sigma_\epsilon^2) \quad (6)$$

**Random Effects:** Alternatively, the effects can be treated as individual but drawn from a distribution  $F(0, \sigma_\alpha^2)$  which is **independent from**  $x_{it}$ .

Think of: Wealth studies, but everyone plays the lottery.

$$y_{it} = \mu + \beta' x_{it} + \alpha_i + u_{it} \quad (7)$$

**Least Squares Dummy Variable (LSDV)** approach:

$$y_{it} = \sum_{j=1}^N \alpha_j d_{ij} + x'_{it} \beta + \epsilon_{it} \quad (8)$$

**Mean Differencing:**

$$\begin{aligned} \bar{y}_i &= \frac{1}{T} \sum_{t=1}^T y_{it} \\ \bar{y}_i &= \alpha_i + \bar{x}'_i + \bar{\epsilon}_i \\ y_{it} - \bar{y}_i &= (x_{it} - \bar{x})' \beta + (\epsilon_{it} - \bar{\epsilon}_i) \quad \alpha_i \text{ drops out} \end{aligned} \quad (9)$$

**First Differencing**

$$\begin{aligned} y_{it} - y_{it-1} &= (\alpha_i - \alpha_i) + (x_{it} - x_{it-1})' \beta + (\epsilon_{it} - \epsilon_{it-1}) \\ \Delta y_{it} &= \Delta x'_{it} \beta + \Delta \epsilon_{it} \end{aligned} \quad (10)$$



**Mean Differenced Models** are also called **within estimations**:

- ▶ Efficiently estimated by **pooled OLS**.
- ▶ **Unbiased only** if covariates are strictly exogenous, ie.  $E[(x_{it} - \bar{x}_i \epsilon_{it})] = 0$  and  $E[x_{it} \epsilon_{is}] = 0 \quad \forall t \neq s \in T$
- ▶ Same estimators but different standard errors as in **LSDV**.
- ▶ Intercept can be retrieved.

$$\hat{\beta}_{FE} = \left( \sum_{i=1}^N \sum_{j=1}^T (x_{it} - \bar{x}_i)(x_{it} - \bar{x}_i)' \right)^{-1} \sum_{i=1}^N \sum_{j=1}^T (x_{it} - \bar{x}_i)(y_{it} - \bar{y}_i) \quad (11)$$

$$\hat{\alpha}_i = \bar{y}_i - \hat{\beta}'_{FE} \bar{x}_i \quad (12)$$

*Note:* In short and wide panels (small T, large N) the **intercept** cannot be efficiently retrieved.

RE allow for serial correlation of error terms and decompose errors in a time-dependent **effect error**  $\alpha_i$  and a time-invariant **error**  $\epsilon_{it}$ .

$$y_{it} = \mu + x'_{it}\beta + u_{it} \quad (13)$$

$$u_{it} = \alpha_i + \epsilon_{it} \quad (14)$$

$$E(\epsilon_{it} \mid x_{it}) = 0 \Rightarrow E(u_{it} \mid \alpha_i, x_{it}) = 0$$

Properties of  $u_{it}$ :

$$E(u_{it}^2) = \sigma_\alpha^2 + \sigma^2 + 2Cov(\alpha_i, u_{it}) = \sigma_\alpha^2 + \sigma^2 \quad (15)$$

$$E(u_{it}u_{is}) = E[(\alpha_i + u_{it})(\alpha_i + u_{is})] = \sigma_\alpha^2 \quad (16)$$

## Estimating Random Effects

- ▶  $\mu$  and  $\beta$  can be consistently estimated by OLS.
- ▶ Standard errors **can not be consistently estimated by OLS**.
- ▶ **GLS** provides consistent and efficient estimation, for  $\iota_T$  a  $T \times 1$  vector of 1s and  $I_T$  the T-dimensional identity matrix.

$$V[\alpha_i \iota_T + \epsilon_{it}] \equiv \Omega = \sigma_\alpha^2 \iota_T \iota_T' + \sigma_\epsilon^2 I_T \quad (17)$$

$$\begin{aligned} \Omega^{-1} &= \sigma_\epsilon^{-2} \left[ I_T - \frac{\sigma_\alpha^2}{\sigma_\epsilon^2 + T\sigma_\alpha^2} \iota_T \iota_T' \right] \\ &= \sigma_\epsilon^{-2} \left[ \left( I_T - \frac{1}{T} \iota_T \iota_T' \right) + \psi \frac{1}{T} \iota_T \iota_T' \right] \\ \psi &= \frac{\sigma_\alpha^2}{\sigma_\epsilon^2 + T\sigma_\alpha^2} \end{aligned} \quad (18)$$

$$\begin{aligned} \hat{\beta}_{GLS} &= \left( \sum_{i=1}^N \sum_{j=1}^T (x_{it} - \bar{x}_i)(x_{it} - \bar{x}_i)' + \psi T \sum_{i=1}^N (\bar{x}_i - \bar{x})(\bar{x}_i - \bar{x})' \right)^{-1} \\ &\quad \times \left( \sum_{i=1}^N \sum_{j=1}^T (x_{it} - \bar{x}_i)(y_{it} - \bar{y}_i)' + \psi T \sum_{i=1}^N (\bar{x}_i - \bar{x})(\bar{y}_i - \bar{y})' \right) \end{aligned} \quad (19)$$

- ▶ The GLS estimator is a **weighted mean** of the between and within estimators with weights  $\lambda$  and  $(1 - \lambda)$ .

$$\hat{\beta}_{GLS} = \lambda \hat{\beta}_B + (1 - \lambda) \hat{\beta}_W \quad (20)$$

$$\hat{\beta}_B = \left( \sum_{i=1}^N (\bar{x}_i - \bar{x})(\bar{x}_i - \bar{x})' \right)^{-1} \left( \sum_{i=1}^N (\bar{x}_i - \bar{x})(\bar{y}_i - \bar{y})' \right)$$

$$\hat{\beta}_W = \left( \sum_{i=1}^N \sum_{j=1}^T (x_{it} - \bar{x}_i)(x_{it} - \bar{x}_i)' \right)^{-1} \sum_{i=1}^N \sum_{j=1}^T (x_{it} - \bar{x}_i)(y_{it} - \bar{y}_i)$$

## Relationship between Panel Estimators

Relationship between FE, RE and Pooled OLS is given by effect heterogeneity  $\sigma_\alpha^2$ .

- ▶ For maximum heterogeneity, FE converges to RE
- ▶ For minimum heterogeneity, RE converges to Pooled OLS
- ▶ FE does not allow for identification of time-invariant covariates (eg. years of schooling among workers).
- ▶ FE identifies differences **within** individuals  $y_{it} - \bar{y}_i$ , not between individuals  $\bar{y}_i - \bar{y}_j$ .
- ▶ RE does not allow for meaningful identification of effects
- ▶ RE identifies the between difference  $\bar{y}_i - \bar{y}$ .
- ▶ RE is **more efficient** for  $\psi = \frac{\sigma_\alpha^2}{\sigma_\epsilon^2 + T\sigma_\alpha^2} > 1$ .

## Model Selection (Hausman Test)

The choice between FE and RE makes a substantial difference in estimating  $\beta$ .

The expected values in FE and RE are the same if  $x_{ij}$  and  $\alpha_i$  are **uncorrelated**  $\Rightarrow$  prefer FE to identify  $\alpha_i$ , or RE for higher efficiency.

**Hausman Test:**  $H_0 : E[x_{it}\alpha_i] = 0$  ;  $H_A : E[x_{it}, \alpha_i] \neq 0$ .

- ▶  $\hat{\beta}_{FE}$  is consistent and efficient under both  $H_0$  and  $H_A$ .
- ▶  $\hat{\beta}_{RE}$  is consistent only under  $H_0$ .
- ▶ Only under  $H_0$ ,  $V[\hat{\beta}_{FE} + \hat{\beta}_{RE}] = V[\hat{\beta}_{FE}] + V[\hat{\beta}_{RE}]$ .

Hausmann test statistic:

$$\xi_H = (\hat{\beta}_{FE} - \hat{\beta}_{RE})' [\hat{V}[\hat{\beta}_{FE}] - \hat{V}[\hat{\beta}_{RE}]]^{-1} (\hat{\beta}_{FE} - \hat{\beta}_{RE}) \quad (21)$$
$$\xi_H \sim \chi^2(K)$$