

Lab 5: Conditional Quantile Regression

Econometrics Beyond Ordinary Least Squares

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Conditional Quantile Regression

- ▶ Koenker and Basset (1978): Apply the **optimization intuition** behind OLS to non-mean moments of dependent variable y .
- ▶ Impact of mean X on **distribution of y** .

Examples:

- ▶ Unionization more important for lower-wage segments.
- ▶ Lawyer expenditures matter more for high-wealth percentiles.
- ▶ Class size has a more negative impact on low than on high course evaluations.
- ▶ Closing of gender gap in wage increases is less accentuated in the top of the distribution.

CQR: Illustration with i.i.d. errors

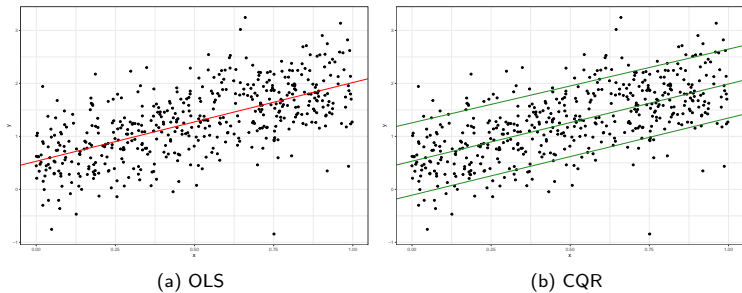


Figure 1: Intercept Shift: OLS and CQR (quantiles 0.1, 0.5 and 0.9) fit lines for i.i.d. errors.

CQR: Illustration with heteroskedastic errors

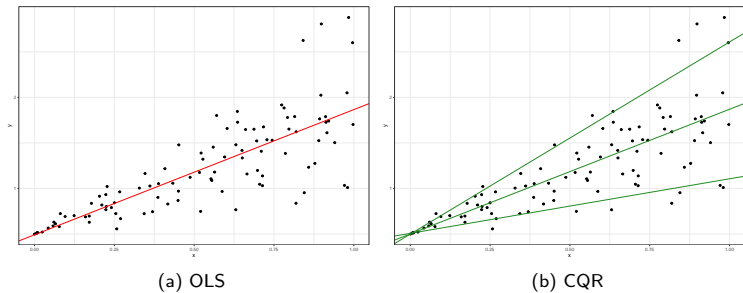


Figure 2: Slope Shift: OLS and CQR (quantiles 0.1, 0.5 and 0.9) fit lines with heteroskedasticity.

OLS: Conditional Expected Value

If $E[\epsilon_i | x_i] = 0$, x_i is **exogenous**.

$E[y_i | x_i] = x_i' \beta$: the **conditional expectation** of y_i .

$\beta = \frac{\partial E[y_i | x_i]}{\partial x_i}$: the **marginal effect** of x_i on the conditional mean of y_i .

Conditional Mean: **Approximation for location parameter** of $F(Y)$.

$$P(Y_t < y) = F(y - x_i' \beta) \quad (1)$$

If $F()$ is precisely known, some efficient **maximum likelihood estimator** for β exists.

If $F()$ is the Gaussian Normal, $\hat{\beta}_{OLS}$ is the **best unbiased linear estimator (BLUE)**.

$\hat{\beta}_{OLS}$ is very sensitive to outliers; and a poor estimator for non-Gaussian Normal $F()$.

OLS: Are errors normally distributed?

The aphorism made famous by Poincare and quoted by Cramèr that, “everyone believes in the [Gaussian] law of errors, the experimenters because they think it is a mathematical theorem, the mathematicians because they think it is an experimental fact,” is still all too apt. This “dogma of normality” as Huber has called it, seems largely attributable to a kind of wishful thinking.

Koenker and Basset, 1978, 34

CQR: Conditional Quantiles

Starting point: Alternative approximation of **location parameter**.

Expansion: **Quantiles** θ_τ of $F(y_i)$, the value that has $100 \times \tau$ % of the observation of the observations below it.

Example: $\theta_{.75}$ of a variable uniformly distributed between 1 and 100 is 75.

$$\theta_\tau : \min_{b \in R} \left[\sum_{i \in i: y_i \geq b} \theta |y_i - b| + \sum_{i \in i: y_i < b} (1 - \theta) |y_i - b| \right] \quad (2)$$

Conditional and Unconditional Quantiles

- ▶ **Conditional Quantiles:** Quantile within group of observations with same covariates. Eg. for $x_i \in$ ('low wage', 'high wage'), $\theta_{0.75}(y_i | x_i = \text{'low wage'})$ the 75th income percentile among low wage earners.
- ▶ **Unconditional Quantiles:** Quantile of the overall sample distribution.

Quantile Regression Coefficients

- ▶ **CQR:** Return of a marginal change in x_i on $y_i | x_i$ while holding x_i constant: Income effect of a Bachelor degree for workers without a Bachelor degree.
- ▶ **UQR:** Return of a marginal change in the population distribution of x_i on the distribution of y_i : How much does the 75th income percentile increase if the share of people with a Bachelor degree increases (marginally).

Strengths:

- ▶ **CQR:** Allows for analysis within subgroups, more granular view.
- ▶ **UQR:** More intuitive interpretation, more general results.

Lehmann (1974): Let x be a **treatment** which you either receive or not; the treatment adds Δy if the untreated response $y \mid x = 0$ would be y .

Two distributions $F(y)$ and $G(y + \Delta(y)) \Rightarrow$ quantile treatment effect $\delta(\tau)$.

$$F(y) = G(y + \Delta(y)) \quad (3)$$

$$\Delta(y) = G^{-1}(F(y)) - y$$

$$\tau = F(y)$$

$$\delta(\tau) = \Delta(F^{-1}(\tau)) = G^{-1}(\tau) - F^{-1}(\tau) \quad (4)$$

Estimate quantile treatment effect for groups n (treatment) and m (control):

$$\hat{\delta}_\tau = \hat{G}_n^{-1} - \hat{F}_m^{-1} \quad (5)$$

CQR Treatment Effects: Idea

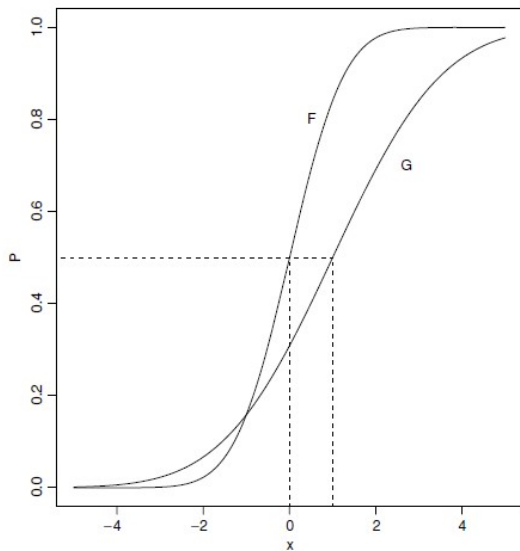


Figure 3: Koenker, 2005, Fig 2.1: “Lehmann quantile treatment effect. Horizontal distance between the treatment and control (marginal) distribution functions.”

CQR Treatment Effects: Standard Cases

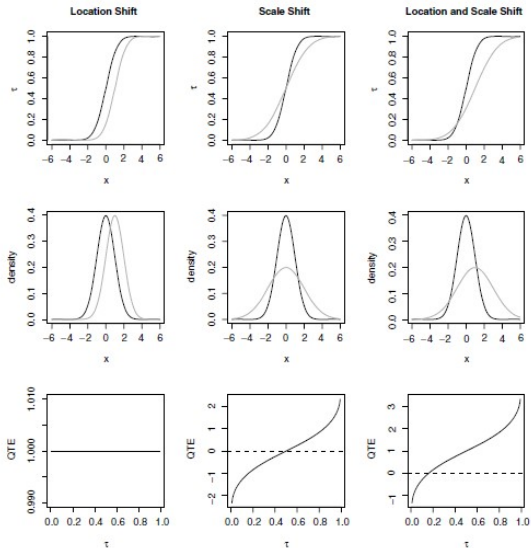


Figure 4: Koenker, 2005, Fig 2.2: “Lehmann quantile treatment effect for three examples. Location shift, scale shift, and location-scale shift.”

CQR Treatment Effects: Skewness Shift

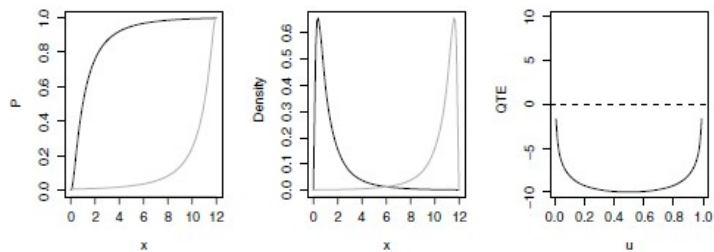


Figure 5: Koenker, 2005, Fig 2.3: “Lehmann quantile treatment effect for an asymmetric example. The treatment reverses the skewness of the distribution function.”

Denote treatments in dummy variable D_{ij} which is 1 if subject i received treatment j .

$$Q_{y_i}(\tau | D_{ij}) = \alpha_\tau + \sum_{j=1}^p \delta_j(\tau) D_{ij} \quad (6)$$

If treatment variation is **continuous** (eg. days of receiving unemployment benefits) and treatment effects are **equidistant**, ie. the effect of increasing days from 2 to 3 is the same as from 9 to 10.

$$Q_{y_i}(\tau | D_{ij}) = \alpha_\tau + \beta(\tau) x_i \quad (7)$$

CQR: Euclidian Distance Loss Function

In OLS, the loss function subject to minimization is the **squared sum of errors** $\sum (y_i - \hat{y})^2$.

For CQR the distance function $\|\hat{y} - y\|$ depends on τ .

$$\begin{aligned}d(\hat{y}, y) &= \sum_i^N \rho_\tau(y_i - \hat{y}_i) \\ &= \sum_i^N \rho_\tau(y_i - x_i \beta(\tau))\end{aligned}\tag{8}$$

$$\hat{\beta}(\tau) : \min_{\beta(\tau)} \sum_i \rho_\tau(y_i - x_i \beta(\tau))\tag{9}$$

Loss function ρ_τ takes different values for $y_i \leq x_i\beta(\tau)$ and $y_i > x_i\beta(\tau)$.

$$\begin{aligned}\rho_\tau(y_i - x_i\beta(\tau)) &= \begin{cases} (y_i - x_i\beta(\tau))(\tau - 1) & \text{if } y_i \leq x_i\beta(\tau) \\ (y_i - x_i\beta(\tau))\tau & \text{if } y_i > x_i\beta(\tau) \end{cases} \\ &= \sum_i ((y_i - x_i\beta(\tau))(\tau - 1))\mathbb{1}(y_i \leq x_i\beta(\tau)) \\ &\quad + \sum_i ((y_i - x_i\beta(\tau))\tau)\mathbb{1}(y_i > x_i\beta(\tau)) \end{aligned} \quad (10)$$

One can efficiently estimate $\hat{\beta}_\tau$ by maximizing the log-likelihood of $\rho_\tau(y_i, x_i\beta_\tau)$

Median $\tau = 0.5$:

- ▶ As many observations below and above Q_τ
- ▶ $\tau = -(\tau - 1)$
- ▶ $\rho_\tau = \sum_{y_i > x_i \beta} (y_i - x_i \beta) - \sum_{y_i \leq x_i \beta} (y_i - x_i \beta) = \sum_i |y_i - x_i \beta|$.

Only constant $y_i = \beta_\tau$:

- ▶ $\frac{\partial}{\partial \beta_\tau} = \sum_i \rho_\tau(y_i - \beta_\tau) = \sum_{y_i \leq \beta_\tau} (\tau - 1) + \sum_{y_i > \beta_\tau} \tau = 0$.
- ▶ Condition only holds if the share of observations with $y_i \leq \beta_\tau$ is τ
- ▶ β_τ is the population percentile τ .

Figure 1. Interpreting conditional quantile regressions

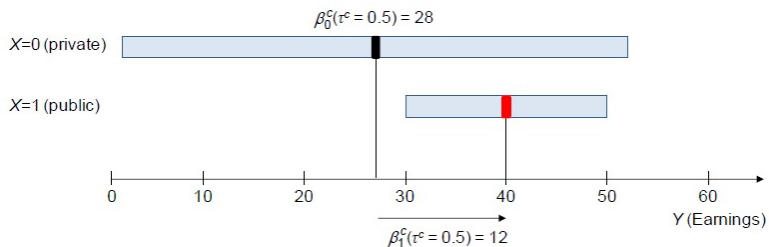


Figure 6: Fournier, 2012, Fig 1: "Interpreting conditional quantile regressions"

Linear programming ($\mathbf{1}_n$ be a n-entry vector of ones):

$$\begin{aligned}
 & \mathbf{u} = \mathbf{X}_i \beta_\tau \\
 & \min_{\beta, \mathbf{u}^+, \mathbf{u}^- \in \mathbb{R}^k \times \mathbb{R}^{2n}} \left[\tau \mathbf{1}'_n \mathbf{u}^+ + (1 - \tau) \mathbf{1}'_n \mathbf{u}^- \mid \mathbf{X} \beta + \mathbf{u}^+ - \mathbf{u}^- = \mathbf{Y} \right] \quad (11) \\
 & \mathbf{u}_j^+ = \max(u_j, 0) ; \mathbf{u}_j^- = \min(u_j, 0)
 \end{aligned}$$

Bayesian Estimation: An asymmetric Laplace (ALD) likelihood is equivalent to the CQR loss function.

$$\max_{\beta} L(\beta) = n \log(q) + n \log(1 - q) - \sum_i^N \rho_\tau(y_i - x_i \beta_\tau) \quad (12)$$

$$\rho_\tau(x) = \frac{|x| + (2q - 1)x}{2}$$

$$y_{ij} - x_{ij} \beta_i \sim \text{ALD}(q)$$

$$\beta_i \sim N(\mu, \Sigma)$$

If errors are i.i.d., the **asymptotic covariance matrix of the errors** $\beta - \beta$ can be approximated from the probability density function and allows for estimation of standard errors.

$$\xi(\theta) = F^{-1}(\theta) ; \xi_i(\theta) = \beta_i^* - \beta$$
$$\sqrt{T}(\xi(\theta_1) - \xi(\theta_1), \dots, \xi(\theta_M) - \xi(\theta_M)) \rightarrow \sim N(0, \Omega) \quad (13)$$

$$\omega_{ij} = \frac{\theta_i(1 - \theta_j)}{f(\xi(\theta_i))f(\xi(\theta_j))} \quad (14)$$

Alternative estimation methods for standard errors in linear programming includes **confidence intervals** from rank tests, Huber sandwich errors, Powell kernel sandwich estimates, and different **bootstrapping techniques**.